



## IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Patent No.:

6,924,730 B1

Docket No.:

EVAN-10044

Inventor:

**Evans** 

Grp Art Unit:

2632

Serial No.:

10/645,004

Issued:

August 2, 2005

Title:

FIRE DOOR CONTROL SYSTEM AND METHOD INCLUDING PERIODIC

**SYSTEM TESTING** 

Certificate

SEP 1 5 2005

Certificate of Correction Branch Commissioner for Patents P.O. Box 1450 Alexandria, VA 22313-1450

of Correction

REQUEST FOR CERTIFICATE OF CORRECTION OF PATENT FOR PTO MISTAKE (37 C.F.R. 1.322(A))

Dear Sir/Madam:

Transmitted herewith is a Certificate of Correction (Form PTO-1050) for U.S. Patent 6,924,730 issued August 2, 2005. Upon reviewing the ribbon copy of the patent, the undersigned noted the following typographical errors. The exact page and line number where the errors are shown correctly in the application filed are:

<u>Page</u>	<u>Line</u>	
Page 23	1 - 26	Of the original filed application
Page 24	1 - 29	Of the original filed application

I HEREB	Y CERTIFY THAT THE CORR	ESPONDENCE TO WHICH T	HIS STATEMENT IS AFFIXED IS BEIN	G DEPOSITED
WITH TI	HE UNITED STATES POSTAL S	ERVICE, POSTAGE PAID, AS	S FIRST CLASS MAIL IN AN ENVELOI	PE ADDRESSED
TO THE	COMMISSIONER OF PATENTS	S AND TRADEMARKS, ALEX	KANDRIA, VA, 22313-1450	
ON:	September 7, 2005	SIGNED: _	Hather Class	K_
			Heather Clark	

Patent No.: 6,924,730

Since the error for which a Certificate of Correction is sought was a result of a Patent and Trademark Office mistake, no fee is due (35 U.S.C. §254). A duplicate copy of the Certificate of Correction is enclosed.

It is respectfully requested that a certified Certificate of Correction be forwarded to the undersigned upon fulfillment of the above. The Honorable Commissioner is hereby authorized to charge Deposit Account No. 19-0513 for any fee that may be due with said request.

Date: September 7, 2005

David E. Allred

Attorney for Applicant

Respectfully submitted,

Reg. No.: 47,254

Schmeiser, Olsen & Watts 18 E. University Dr. Mesa, Arizona 85201 (480) 655-0073

## UNITED STATES PATENT AND TRADEMARK OFFICE CERTIFICATE OF CORRECTION

PATENT NO. : 6,924,730 B \

DATED : August 2, 2005

INVENTOR(S): Evans

It is certified that an error appears or errors appear in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

In the Specification, column 12, line number 58, please insert the following after "...460 are only one mechanism by which the..."

--automatic brake release can be implemented. The linkage could be any of the variety of linkages that could incorporate levers, sliding mechanisms, or gears, for example.

Figure 6B is a rear plan view of the hand crank hoist 370 of Figure 6A and clarifies specific structure of the guides 450, 455. As shown, the guides 450, 455 comprise channels 465, 470 through which the endless element 380 passes. In this way inadvertent falling out of the endless element 380 from the guides 450, 455 is prevented, and a point of application of a force on the bell crank 435 at a position outwardly of vertical lines tangent to the input pulley 390 is assured. Thus, pulling vertically downward on the endless element 380 will always rotate the bell crank 435.

Figure 7 depicts a method of controlling a fire door control system in a normal running mode with no alarm condition present. As shown, the fire door system has a starting point with the door in an open condition at 475. A first step 480 includes pressing a close button. A second step 485, which is optional and is only implemented in some configurations of the system and method, includes initiating an audio and/or visual alert and a time delay before closing the door. This is beneficial for notifying persons in the vicinity that the door will be closing and for giving them a chance to get away from the door. A third step 490 includes closing the door. During the door closing condition, a controller awaits a signal from a safety sensor such as an edge trip sensor in a lower edge of a rollable door. Thus, a forth step 495 includes checking if a safety sensor has been tripped. If the safety sensor is tripped during the closing condition of the door an additional step 500 including reversing the door and moving the door to a fully open position is effected. In the fully opened condition 475 the door is ready for additional active input. On the other hand, if the safety edge is not tripped, the door continues to close until the door closed condition 505 is reached. In the door closed condition the door control system is ready for the fifth step 510 of opening the door by pressing an open button.

It is to be understood that in the method of controlling a fire door system under normal running conditions with no alarm condition present, a stop button could be pressed at any time to stop the door in its current position. In accordance with this method, the edge safety sensor is not active when the door is in a door opening condition. It is to be understood that the controller could be implemented as a mechanical, chemical, electrical, or combination controller. On the other hand, the controller for the present method is typically an electronic and/or electromechanical controller. Relatedly, the safety sensor can be implemented as an electro-mechanical contact strip run along a lower edge of the fire door so that when the lower edge contacts an obstruction between the fully up and the fully down positions, the contact strip is pressed and a signal is sent to the controller. Alternatively, the safety sensor can include one or more of a motion sensor, an optical sensor of the type that incorporates lasers or infrared beams, or a transponder type sensor. The safety sensor can be one of a plurality of safety sensors that can be located at positions other than on a lower edge of the fire door. These safety sensors are to be incorporated on doors that have power drive mechanisms, hand crank hoist drive mechanisms, as well as doors that are raised by hand.

In accordance with the foregoing method of controlling a fire door control system for example, the fire door system can receive an alarm condition at any time during a normal running mode. Figures 8A and 8B are a flow chart depicting the method of controlling the fire door control system when an alarm condition 512 is received in the controller as shown in an upper portion of Figure 8A. When according to step 512 an alarm condition signal is received in the controller, the controller initiates a step 515 of checking to see if the door is open. If the door is open, the controller implements a step 520 of checking to see if the hand hoist is engaged. If the door is closed, then the controller implements a step 525 of initiating an audio and/or visual alert that the door is closed, as shown near the bottom of Figure 8B. After the alert indicating that the fire door is closed, the system is ready for a step 530 of removing the alarm condition and resetting the system. Thus, step 530 can represent two steps. The first step can be that of removing an alarm condition, such as in a fire alarm system in a building where the fire--

In the Specification, please delete starting in Column 13, from line 33 beginning with "...automatic brake release can..." and ending with Column 14, line number 47 "...alarm system in a building where the fire..."

MAILING ADDRESS OF SENDER (Please do not use customer number

PATENT NO. \_6,924,730

No. of additional copies

Reg. No. 47,254 SCHMEISER, OLSEN & WATTS LLP

18 E. University Dr. #101 Mesa, AZ 85201

David E. Allred

**---**

SEP 1 6 2005

## UNITED STATES PATENT AND TRADEMARK OFFICE CERTIFICATE OF CORRECTION

PATENT NO. : 6,924,730 B1

DATED : August 2, 2005

INVENTOR(S): Evans

It is certified that an error appears or errors appear in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

In the Specification, column 12, line number 58, please insert the following after "...460 are only one mechanism by which the..."

--automatic brake release can be implemented. The linkage could be any of the variety of linkages that could incorporate levers, sliding mechanisms, or gears, for example.

Figure 6B is a rear plan view of the hand crank hoist 370 of Figure 6A and clarifies specific structure of the guides 450, 455. As shown, the guides 450, 455 comprise channels 465, 470 through which the endless element 380 passes. In this way inadvertent falling out of the endless element 380 from the guides 450, 455 is prevented, and a point of application of a force on the bell crank 435 at a position outwardly of vertical lines tangent to the input pulley 390 is assured. Thus, pulling vertically downward on the endless element 380 will always rotate the bell crank 435.

Figure 7 depicts a method of controlling a fire door control system in a normal running mode with no alarm condition present. As shown, the fire door system has a starting point with the door in an open condition at 475. A first step 480 includes pressing a close button. A second step 485, which is optional and is only implemented in some configurations of the system and method, includes initiating an audio and/or visual alert and a time delay before closing the door. This is beneficial for notifying persons in the vicinity that the door will be closing and for giving them a chance to get away from the door. A third step 490 includes closing the door. During the door closing condition, a controller awaits a signal from a safety sensor such as an edge trip sensor in a lower edge of a rollable door. Thus, a forth step 495 includes checking if a safety sensor has been tripped. If the safety sensor is tripped during the closing condition of the door an additional step 500 including reversing the door and moving the door to a fully open position is effected. In the fully opened condition 475 the door is ready for additional active input. On the other hand, if the safety edge is not tripped, the door continues to close until the door closed condition 505 is reached. In the door closed condition the door control system is ready for the fifth step 510 of opening the door by pressing an open button.

It is to be understood that in the method of controlling a fire door system under normal running conditions with no alarm condition present, a stop button could be pressed at any time to stop the door in its current position. In accordance with this method, the edge safety sensor is not active when the door is in a door opening condition. It is to be understood that the controller could be implemented as a mechanical, chemical, electrical, or combination controller. On the other hand, the controller for the present method is typically an electronic and/or electromechanical controller. Relatedly, the safety sensor can be implemented as an electro-mechanical contact strip run along a lower edge of the fire door so that when the lower edge contacts an obstruction between the fully up and the fully down positions, the contact strip is pressed and a signal is sent to the controller. Alternatively, the safety sensor can include one or more of a motion sensor, an optical sensor of the type that incorporates lasers or infrared beams, or a transponder type sensor. The safety sensor can be one of a plurality of safety sensors that can be located at positions other than on a lower edge of the fire door. These safety sensors are to be incorporated on doors that have power drive mechanisms, hand crank hoist drive mechanisms, as well as doors that are raised by hand.

In accordance with the foregoing method of controlling a fire door control system for example, the fire door system can receive an alarm condition at any time during a normal running mode. Figures 8A and 8B are a flow chart depicting the method of controlling the fire door control system when an alarm condition 512 is received in the controller as shown in an upper portion of Figure 8A. When according to step 512 an alarm condition signal is received in the controller, the controller initiates a step 515 of checking to see if the door is open. If the door is open, the controller implements a step 520 of checking to see if the hand hoist is engaged. If the door is closed, then the controller implements a step 525 of initiating an audio and/or visual alert that the door is closed, as shown near the bottom of Figure 8B. After the alert indicating that the fire door is closed, the system is ready for a step 530 of removing the alarm condition and resetting the system. Thus, step 530 can represent two steps. The first step can be that of removing an alarm condition, such as in a fire alarm system in a building where the fire-

In the Specification, please delete starting in Column 13, from line 33 beginning with "...automatic brake release can..." and ending with Column 14, line number 47 "...alarm system in a building where the fire..."

MAILING ADDRESS OF SENDER (Please do not use customer number

PATENT NO. 6,924,730

No. of additional copies

Reg. No. 47,254
SCHMEISER, OLSEN & WATTS LLP

18 E. University Dr. #101 Mesa, AZ 85201

David E. Allred

<del>----</del>

SEP 1 6 2005